# Pseudo anti-commuting and Ricci soliton real hypersurfaces in complex two-plane Grassmannians 

Imsoon Jeong, Young Jin Suh*<br>Department of Mathematics, Kyungpook National University, Taegu 702-701, Republic of Korea

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#### Abstract

In this paper, first we introduce a new notion of pseudo anti-commuting for real hypersurfaces in complex two-plane Grassmannians $G_{2}\left(\mathbb{C}^{m+2}\right)$ and prove a complete classification theorem, which gives a shrinking Ricci soliton with potential Reeb flow on Hopf real hypersurfaces and a tube over a totally real totally geodesic $\mathbb{Q} P^{n}, m=2 n$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$.


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## 0. Introduction

In the geometry of real hypersurfaces in complex space forms $M_{m}(c)$ or in quaternionic space forms $Q_{m}(c)$ Okumura [1], Kimura [2], Montiel and Romero [3] (resp. Martinez and Pérez [4]) considered real hypersurfaces in $M_{n}(c)$ (resp. in $Q_{m}(c)$ ) with commuting shape operator, that is, $A \phi=\phi A$, or commuting Ricci tensor, $S \phi=\phi S$, where $S$ and $\phi$ (resp. $A$ and $\phi_{i}$ ) denote the Ricci tensor and the structure tensor of real hypersurfaces in $M_{m}(c)$ (resp. in $Q_{m}(c)$ ).

In a quaternionic projective space $\mathbb{Q} P^{m}$ Pérez and Suh [5] have classified real hypersurfaces in $Q P^{m}$ with commuting Ricci tensor $S \phi_{i}=\phi_{i} S, i=1,2,3$, where $S$ (resp. $\phi_{i}$ ) denotes the Ricci tensor (resp. the structure tensor) of $M$ in $\mathbb{Q} P^{m}$, is locally congruent to $A_{1}, A_{2}$-type, that is, a tube over $\mathbb{Q} P^{k}$ with radius $0<r<\frac{\pi}{2}, k \in\{0, \ldots, m-1\}$. The almost contact structure vector fields $\left\{\xi_{1}, \xi_{2}, \xi_{3}\right\}$ are defined by $\xi_{i}=-J_{i} N, i=1,2$, 3, where $J_{i}, i=1,2,3$, denote a quaternionic Kähler structure of $\mathbb{Q} P^{m}$ and $N$ a unit normal field of $M$ in $\mathbb{Q} P^{m}$. Moreover, Pérez and Suh [6] have considered the notion of $\nabla_{\xi_{i}} R=0, i=1,2,3$, where $R$ denotes the curvature tensor of a real hypersurface $M$ in $\mathbb{Q} P^{m}$, and proved that $M$ is locally congruent to a tube of radius $\frac{\pi}{4}$ over $\mathbb{Q} P^{k}$.

In paper [7] the author considered a real hypersurface $M$ in complex two-plane Grassmannians $G_{2}\left(\mathbb{C}^{m+2}\right)$ with commuting Ricci tensor, $S \phi=\phi S$, where $S$ and $\phi$ denote the Ricci tensor and the structure tensor of $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$, respectively. The curvature tensor $R(X, Y) Z$ of $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ can be derived from the curvature tensor $\bar{R}(X, Y) Z$ of complex two-plane Grassmannians $G_{2}\left(\mathbb{C}^{m+2}\right)$ for any vector fields $X, Y$ and $Z$ on $M$. Then by contraction and using the geometric structure

[^0]$J J_{i}=J_{i} J, i=1,2,3$ between the Kähler structure $J$ and the quaternionic Kähler structure $J_{i}, i=1,2$, 3 , we can derive the Ricci tensor $S$ given by (see Section 3)
$$
g(S X, Y)=\sum_{i=1}^{4 m-1} g\left(R\left(e_{i}, X\right) Y, e_{i}\right)
$$
where $\left\{e_{1}, \ldots, e_{4 m-1}\right\}$ denotes a basis of the tangent space $T_{x} M$ of $M, x \in M$, in $G_{2}\left(\mathbb{C}^{m+2}\right)$.
When the Ricci tensor $S$ and the structure tensor $\phi$ commutes like $S \phi=-\phi S$, the Ricci tensor is said to be anticommuting. Motivated by such a notion of anti-commuting, we consider a new notion so called pseudo-anti commuting Ricci tensor if the Ricci tensor satisfies the formula
$$
S \phi+\phi S=2 k \phi, \quad k=\text { const. }
$$

It is known that Einstein, pseudo-Einstein real hypersurfaces in the sense of Kon [8], Cecil and Ryan [9], real hypersurfaces of type (B), which is a tube over a totally real totally geodesic real projective space $\mathbb{R} H^{n}, m=2 n$, in $M_{m}$ (c) satisfy the formula (see Yano and Kon [10]). Moreover, it can be easily checked that Einstein hypersurfaces and some special kind of pseudo Einstein hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$, and hypersurfaces of type (B), which is a tube over a totally real totally geodesic quaternionic projective space $\mathbb{Q} H^{n}, m=2 n$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ satisfy this formula (see Berndt and Suh [11], Pérez, Suh and Watanabe [12]).

On the other hand, the ambient space $G_{2}\left(\mathbb{C}^{m+2}\right)$ is known to be the unique compact irreducible Riemannian symmetric space equipped with both a Kähler structure $J$ and a quaternionic Kähler structure $\mathfrak{J}$ not containing $J$ (see Berndt and Suh [11], [13]). So, in $G_{2}\left(\mathbb{C}^{m+2}\right)$ we have two natural geometrical conditions for real hypersurfaces that $[\xi]=$ Span $\{\xi\}$ or $\mathfrak{D}^{\perp}=\operatorname{Span}\left\{\xi_{1}, \xi_{2}, \xi_{3}\right\}$ is invariant under the shape operator. By using such kinds of geometric conditions and the result in Alekseevskii [14], Berndt and Suh [11] have proved the following.

Theorem A. Let $M$ be a connected real hypersurface in $G_{2}\left(\mathbb{C}^{m+2}\right), m \geq 3$. Then both $[\xi]$ and $\mathfrak{D}^{\perp}$ are invariant under the shape operator of $M$ if and only if
(A) $M$ is an open part of a tube around a totally geodesic $G_{2}\left(\mathbb{C}^{m+1}\right)$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$, or
(B) $m$ is even, say $m=2 n$, and $M$ is an open part of a tube around a totally geodesic $\mathbb{Q} P^{n}$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$.

When the structure vector field $\xi$ of $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ is invariant by the shape operator $A, M$ is said to be a Hopf hypersurface. In such a case the integral curves of the structure vector field $\xi$ are geodesics (see Berndt and Suh [13]). The flow generated by the integral curves of the structure vector field $\xi$ for Hopf hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$ is said to be a geodesic Reeb flow.

On the other hand, we say that the Reeb vector field is Killing, that is, $\mathscr{L}_{\xi} g=0$ for the Lie derivative along the direction of the structure vector field $\xi$, which gives a characterization of real hypersurfaces of type (A) in Theorem A.

When the Ricci tensor $S$ of $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ satisfies the formula $S \phi+\phi S=2 k \phi, k=$ const, we say that $M$ has a pseudo anti-commuting Ricci tensor.

In the proof of Theorem A we have proved that the one-dimensional distribution [ $\xi$ ] belongs to either the 3-dimensional distribution $\mathfrak{D}^{\perp}$ or to the orthogonal complement $\mathfrak{D}$ such that $T_{x} M=\mathfrak{D} \oplus \mathfrak{D}^{\perp}$. The case (A) in Theorem A is just the case that the one dimensional distribution [ $\xi$ ] belongs to the distribution $\mathfrak{D}^{\perp}$. Of course they satisfy that the Reeb vector $\xi$ is Killing, that is, the structure tensor $\phi$ commutes with the shape operator $A$.

Recently, we have known that a solution of the Ricci flow equation $\frac{\partial}{\partial t} g(t)=-2 \operatorname{Ric}(g(t))$, is given by

$$
\frac{1}{2}\left(\mathfrak{L}_{\xi} g\right)(X, Y)+\operatorname{Ric}(X, Y)=\operatorname{kg}(X, Y)
$$

where $k$ is a constant and $\mathfrak{L}_{\xi}$ denotes the Lie derivative along the direction of the Reeb vector field $\xi$. Then the solution is said to be a Ricci soliton, and surprisingly, it satisfies the pseudo-anti commuting condition $S \phi+\phi S=2 k \phi$.

In this paper we consider such a converse problem and want to give a complete classification of real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$ satisfying $S \phi+\phi S=2 k \phi$. In order to do this, first we assert the following theorem.

Theorem 1. Let $M$ be a Hopf hypersurface in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with pseudo anti-commuting Ricci tensor, $m \geq 3$. Then we have one of the following
(i) $k=4 m+2+\frac{\alpha}{2}(h-\alpha)$ for $\xi \in \mathfrak{D}^{\perp}$, where $\alpha=g(A \xi, \xi)$ and $h$ denotes the mean curvature of $M$.
(ii) $M$ is locally congruent to a tube of radius $r$ over a totally geodesic and totally real quaternionic projective space $\mathbb{Q} P^{m}$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ for $\xi \in \mathfrak{D}$.

When the constant $k$ is equal to $4 m+2+\frac{\alpha}{2}(h-\alpha)$, we will show that a nice geometric and cosmological structure could be given for hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$ satisfying certain condition. In order to do this, let us recall an $n$-dimensional Riemannian manifold $(M, g)$ is said to be a Ricci soliton if there exists a smooth vector field $V \in T_{x} M, x \in M$ that satisfies for any $X, Y \in T M$

$$
\frac{1}{2}\left(\mathfrak{L}_{V} g\right)(X, Y)+\operatorname{Ric}(X, Y)=k g(X, Y)
$$

where $\mathfrak{L}_{V} g$ denotes the Lie derivative of $g$ with respect to the vector field $V$ and $k$ a constant (see Chow et al. [15]). We will denote the Ricci soliton by ( $M, g, V, k$ ) and call the vector field $V$ as the potential vector field of the Ricci soliton. A Ricci soliton $(M, g, V, k)$ is said to be a stable, expanding or shrinking according to $k=0, k<0$ or $k>0$.

When the potential vector field $V$ of the Ricci soliton ( $M, g, V, k$ ) is a Killing vector field, $M$ becomes an Einstein manifold. It is known that the Ricci tensor $S$ of an Einstein hypersurface $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ is given by $S=a g$ for a constant $a$, that is, $\operatorname{Ric}(X, Y)=a g(X, Y)$ for any $X$ and $Y$ on $M$ and a Riemannian metric $g$ defined on $M$. Naturally the Ricci tensor $S$ commutes with the structure tensor $\phi$, that is, $S \phi=\phi S$. So by virtue of a theorem due to the author [7] it becomes a hypersurfaces of type $(A)$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$. But by Proposition B in Section 5 it can be easily checked that any tubes of radius $r$ over a totally geodesic $G_{2}\left(\mathbb{C}^{m+1}\right)$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ cannot be Einstein (see [12]). This means that among real hypersurfaces of type $(\mathrm{A})$ there do not exist any Ricci solitons in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with the Killing potential vector field.

But, besides of this one, we can also assert that there do not exist any Ricci soliton on real hypersurfaces of type B mentioned (ii) in Theorem 1. Then as an application of Theorem 1 in the direction of Math. Physics, we give another theorem as follows:

Theorem 2. Let $M$ be a Hopf real hypersurface in $G_{2}\left(\mathbb{C}^{m+2}\right), m \geq 3$ with potential Reeb field $\xi$ and Ricci soliton constant $k$. Then $k=4(m+1)>0$ and the Ricci soliton $(M, g, \xi, k)$ becomes a shrinking Ricci soliton.

By Theorem 2 and using the result given in Chow and etc. (see p. 7 in [15]), we know that any shrinking Ricci soliton on a closed $n$-manifold has positive curvature. Then as another geometric result from such a topological point of a view, by Theorem 2 we assert the following.

Corollary. Let $M$ be a closed Hopf real hypersurface in $G_{2}\left(\mathbb{C}^{m+2}\right), m \geq 3$ with potential Reeb field $\xi$ and Ricci soliton constant $k$. Then the Ricci soliton $(M, g, \xi, k)$ has a positive scalar curvature.

In Section 2 we recall Riemannian geometry of complex two-plane Grassmannians $G_{2}\left(\mathbb{C}^{m+2}\right)$ and in Section 3 we will show some fundamental properties of real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$. The formula for the Ricci tensor $S$ and its covariant derivative $\nabla S$ will be shown explicitly in this section. In Sections 4 and 5 we will give a complete proof of our Theorem 1 according to the geodesic Reeb flow satisfying $\xi \in \mathfrak{D}$ or the geodesic Reeb flow satisfying $\xi \in \mathfrak{D}^{\perp}$. Finally, in Section 6 we introduce the notion of Ricci soliton given by Chow et al. [15] and make its applications to real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$ and prove our Theorem 2. Moreover, related to the pseudo-anti commuting, we will give some remarks about proper pseudoEinstein, Lie $\xi$ invariant and harmonic curvature, and finally non existence of Ricci soliton on ruled real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$.

## 1. Riemannian geometry of $G_{2}\left(\mathbb{C}^{m+2}\right)$

In this section we summarize basic material about $G_{2}\left(\mathbb{C}^{m+2}\right)$, for details we refer to [11,13,16,7,17,17]. By $G_{2}\left(\mathbb{C}^{m+2}\right)$ we denote the set of all complex two-dimensional linear subspaces in $\mathbb{C}^{m+2}$. The special unitary group $G=S U(m+2)$ acts transitively on $G_{2}\left(\mathbb{C}^{m+2}\right)$ with stabilizer isomorphic to $K=S(U(2) \times U(m)) \subset G$. Then $G_{2}\left(\mathbb{C}^{m+2}\right)$ can be identified with the homogeneous space $G / K$, which we equip with the unique analytic structure for which the natural action of $G$ on $G_{2}\left(\mathbb{C}^{m+2}\right)$ becomes analytic. Denote by $\mathfrak{g}$ and $\mathfrak{k}$ the Lie algebra of $G$ and $K$, respectively, and by $\mathfrak{m}$ the orthogonal complement of $\mathfrak{k}$ in $\mathfrak{g}$ with respect to the Cartan-Killing form $B$ of $\mathfrak{g}$. Then $\mathfrak{g}=\mathfrak{k} \oplus \mathfrak{m}$ is an $\operatorname{Ad}(K)$-invariant reductive decomposition of $\mathfrak{g}$. We put $o=e K$ and identify $T_{o} G_{2}\left(\mathbb{C}^{m+2}\right)$ with $\mathfrak{m}$ in the usual manner. Since $B$ is negative definite on $\mathfrak{g}$, its negative restricted to $\mathfrak{m} \times \mathfrak{m}$ yields a positive definite inner product on $\mathfrak{m}$. $\operatorname{By} A d(K)$-invariance of $B$ this inner product can be extended to a $G$-invariant Riemannian metric $g$ on $G_{2}\left(\mathbb{C}^{m+2}\right)$. In this way $G_{2}\left(\mathbb{C}^{m+2}\right)$ becomes a Riemannian homogeneous space, even a Riemannian symmetric space. For computational reasons we normalize $g$ such that the maximal sectional curvature of $\left(G_{2}\left(\mathbb{C}^{m+2}\right), g\right)$ is eight.

The Lie algebra $\mathfrak{k}$ has the direct sum decomposition $\mathfrak{k}=\mathfrak{s u}(m) \oplus \mathfrak{s u}(2) \oplus \mathfrak{R}$, where $\mathfrak{R}$ is the center of $\mathfrak{k}$. Viewing $\mathfrak{k}$ as the holonomy algebra of $G_{2}\left(\mathbb{C}^{m+2}\right)$, the center $\mathfrak{R}$ induces a Kähler structure $J$ and the $\mathfrak{s u}(2)$-part a quaternionic Kähler structure $\mathfrak{J}$ on $G_{2}\left(\mathbb{C}^{m+2}\right)$. If $J_{1}$ is any almost Hermitian structure in $\mathfrak{J}$, then $J J_{1}=J_{1} J$, and $J J_{1}$ is a symmetric endomorphism with $\left(J J_{1}\right)^{2}=I$ and $\operatorname{tr}\left(J J_{1}\right)=0$. This fact will be used in next sections.

A canonical local basis $J_{1}, J_{2}, J_{3}$ of $\mathfrak{J}$ consists of three local almost Hermitian structures $J_{\nu}$ in $\mathfrak{J}$ such that $J_{\nu} J_{\nu+1}=J_{\nu+2}=$ $-J_{v+1} J_{v}$, where the index is taken module three. Since $\mathfrak{J}$ is parallel with respect to the Riemannian connection $\nabla$ of $\left(G_{2}\left(\mathbb{C}^{m+2}\right), g\right)$, there exist for any canonical local basis $J_{1}, J_{2}, J_{3}$ of $\mathfrak{J}$ three local one-forms $q_{1}, q_{2}, q_{3}$ such that

$$
\begin{equation*}
\bar{\nabla}_{X} J_{v}=q_{v+2}(X) J_{v+1}-q_{v+1}(X) J_{v+2} \tag{1.1}
\end{equation*}
$$

for all vector fields $X$ on $G_{2}\left(\mathbb{C}^{m+2}\right)$.
Let $p \in G_{2}\left(\mathbb{C}^{m+2}\right)$ and $W$ a subspace of $T_{p} G_{2}\left(\mathbb{C}^{m+2}\right)$. We say that $W$ is a quaternionic subspace of $T_{p} G_{2}\left(\mathbb{C}^{m+2}\right)$ if $J W \subset W$ for all $J \in \mathfrak{J}_{p}$. And we say that $W$ is a totally complex subspace of $T_{p} G_{2}\left(\mathbb{C}^{m+2}\right)$ if there exists a one-dimensional subspace $\mathfrak{V}$ of $\mathfrak{J}_{p}$ such that $J W \subset W$ for all $J \in \mathfrak{V}$ and $J W \perp W$ for all $J \in \mathfrak{V}^{\perp} \subset \mathfrak{J}_{p}$. Here, the orthogonal complement of $\mathfrak{V}$ in $\mathfrak{J}_{p}$ is taken with respect to the bundle metric and orientation on $\mathfrak{J}$ for which any local oriented orthonormal frame field of $\mathfrak{J}$ is a canonical local basis of $\mathfrak{J}$. A quaternionic (resp. totally complex) submanifold of $G_{2}\left(\mathbb{C}^{m+2}\right)$ is a submanifold all of whose tangent spaces are quaternionic (resp. totally complex) subspaces of the corresponding tangent spaces of $G_{2}\left(\mathbb{C}^{m+2}\right)$.

The Riemannian curvature tensor $\bar{R}$ of $G_{2}\left(\mathbb{C}^{m+2}\right)$ is locally given by

$$
\begin{align*}
\bar{R}(X, Y) Z= & g(Y, Z) X-g(X, Z) Y+g(J Y, Z) J X-g(J X, Z) J Y-2 g(J X, Y) J Z \\
& +\sum_{\nu=1}^{3}\left\{g\left(J_{\nu} Y, Z\right) J_{\nu} X-g\left(J_{\nu} X, Z\right) J_{\nu} Y-2 g\left(J_{\nu} X, Y\right) J_{\nu} Z\right\}+\sum_{\nu=1}^{3}\left\{g\left(J_{\nu} J Y, Z\right) J_{\nu} J X-g\left(J_{\nu} J X, Z\right) J_{\nu} J Y\right\} \tag{1.2}
\end{align*}
$$

where $J_{1}, J_{2}, J_{3}$ is any canonical local basis of $\mathfrak{J}$.

## 2. Some fundamental formulas

In this section we derive some fundamental formulas which will be used in the proof of our main theorem. Let $M$ be a real hypersurface in $G_{2}\left(\mathbb{C}^{m+2}\right)$, that is, a submanifold in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with real codimension one. The induced Riemannian metric on $M$ will also be denoted by $g$, and $\nabla$ denotes the Riemannian connection of $(M, g)$. Let $N$ be a local unit normal field of $M$ and $A$ the shape operator of $M$ with respect to $N$.

The Kähler structure $J$ of $G_{2}\left(\mathbb{C}^{m+2}\right)$ induces on $M$ an almost contact metric structure $(\phi, \xi, \eta, g)$. Furthermore, let $J_{1}, J_{2}, J_{3}$ be a canonical local basis of $\mathfrak{J}$. Then each $J_{\underline{v}}$ induces an almost contact metric structure $\left(\phi_{v}, \xi_{v}, \eta_{v}, g\right)$ on $M$. Using the above expression (1.2) for the curvature tensor $\bar{R}$, the Gauss and the Codazzi equations are respectively given by

$$
\begin{aligned}
R(X, Y) Z= & g(Y, Z) X-g(X, Z) Y+g(\phi Y, Z) \phi X-g(\phi X, Z) \phi Y-2 g(\phi X, Y) \phi Z \\
& +\sum_{\nu=1}^{3}\left\{g\left(\phi_{\nu} Y, Z\right) \phi_{\nu} X-g\left(\phi_{\nu} X, Z\right) \phi_{\nu} Y-2 g\left(\phi_{\nu} X, Y\right) \phi_{\nu} Z\right\} \\
& +\sum_{\nu=1}^{3}\left\{g\left(\phi_{\nu} \phi Y, Z\right) \phi_{\nu} \phi X-g\left(\phi_{\nu} \phi X, Z\right) \phi_{\nu} \phi Y\right\}-\sum_{v=1}^{3}\left\{\eta(Y) \eta_{v}(Z) \phi_{\nu} \phi X-\eta(X) \eta_{v}(Z) \phi_{\nu} \phi Y\right\} \\
& -\sum_{\nu=1}^{3}\left\{\eta(X) g\left(\phi_{\nu} \phi Y, Z\right)-\eta(Y) g\left(\phi_{\nu} \phi X, Z\right)\right\} \xi_{v}+g(A Y, Z) A X-g(A X, Z) A Y
\end{aligned}
$$

and

$$
\begin{aligned}
\left(\nabla_{X} A\right) Y-\left(\nabla_{Y} A\right) X= & \eta(X) \phi Y-\eta(Y) \phi X-2 g(\phi X, Y) \xi+\sum_{\nu=1}^{3}\left\{\eta_{\nu}(X) \phi_{\nu} Y-\eta_{\nu}(Y) \phi_{\nu} X-2 g\left(\phi_{\nu} X, Y\right) \xi_{v}\right\} \\
& +\sum_{\nu=1}^{3}\left\{\eta_{\nu}(\phi X) \phi_{\nu} \phi Y-\eta_{\nu}(\phi Y) \phi_{\nu} \phi X\right\}+\sum_{\nu=1}^{3}\left\{\eta(X) \eta_{\nu}(\phi Y)-\eta(Y) \eta_{\nu}(\phi X)\right\} \xi_{v}
\end{aligned}
$$

where $R$ denotes the curvature tensor of $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$.
The following identities can be proved in a straightforward method and will be used frequently in subsequent calculations (see [12,16,7,18]):

$$
\begin{align*}
& \phi_{v+1} \xi_{v}=-\xi_{v+2}, \quad \phi_{v} \xi_{v+1}=\xi_{v+2}, \\
& \phi \xi_{v}=\phi_{v} \xi, \quad \eta_{v}(\phi X)=\eta\left(\phi_{v} X\right) \\
& \phi_{v} \phi_{v+1} X=\phi_{v+2} X+\eta_{v+1}(X) \xi_{v}  \tag{2.1}\\
& \phi_{v+1} \phi_{v} X=-\phi_{v+2} X+\eta_{v}(X) \xi_{v+1} .
\end{align*}
$$

Now let us put

$$
J X=\phi X+\eta(X) N, \quad J_{v} X=\phi_{v} X+\eta_{v}(X) N
$$

for any tangent vector $X$ of a real hypersurface $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$, where $N$ denotes a normal vector of $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$. Then from this and the formulas (1.1) and (2.1) we have that

$$
\begin{align*}
& \left(\nabla_{X} \phi\right) Y=\eta(Y) A X-g(A X, Y) \xi, \quad \nabla_{X} \xi=\phi A X  \tag{2.2}\\
& \nabla_{X} \xi_{v}=q_{v+2}(X) \xi_{v+1}-q_{v+1}(X) \xi_{v+2}+\phi_{v} A X  \tag{2.3}\\
& \left(\nabla_{X} \phi_{v}\right) Y=-q_{v+1}(X) \phi_{v+2} Y+q_{v+2}(X) \phi_{v+1} Y+\eta_{v}(Y) A X-g(A X, Y) \xi_{v} \tag{2.4}
\end{align*}
$$

Summing up these formulas, we find the following

$$
\begin{align*}
\nabla_{X}\left(\phi_{\nu} \xi\right) & =\nabla_{X}\left(\phi \xi_{v}\right) \\
& =\left(\nabla_{X} \phi\right) \xi_{v}+\phi\left(\nabla_{X} \xi_{v}\right) \\
& =q_{v+2}(X) \phi_{v+1} \xi-q_{v+1}(X) \phi_{v+2} \xi+\phi_{v} \phi A X-g(A X, \xi) \xi_{v}+\eta\left(\xi_{v}\right) A X \tag{2.5}
\end{align*}
$$

Moreover, from $J J_{v}=J_{v} J, v=1,2$, 3, it follows that

$$
\begin{equation*}
\phi \phi_{\nu} X=\phi_{\nu} \phi X+\eta_{\nu}(X) \xi-\eta(X) \xi_{v} \tag{2.6}
\end{equation*}
$$

## 3. Proof of main theorem

In this section let us consider a real hypersurface $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with commuting Ricci tensor, that is, $S \phi=\phi S$.
Now let us contract $Y$ and $Z$ in the equation of Gauss in Section 2. Then the Ricci tensor $S$ of a real hypersurface $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ is given by

$$
\begin{align*}
S X= & \sum_{i=1}^{4 m-1} R\left(X, e_{i}\right) e_{i} \\
= & (4 m+10) X-3 \eta(X) \xi-3 \sum_{\nu=1}^{3} \eta_{\nu}(X) \xi_{v}+\sum_{v=1}^{3}\left\{\left(\operatorname{Tr} \phi_{\nu} \phi\right) \phi_{\nu} \phi X-\left(\phi_{\nu} \phi\right)^{2} X\right\} \\
& -\sum_{\nu=1}^{3}\left\{\eta_{\nu}(\xi) \phi_{\nu} \phi X-\eta(X) \phi_{\nu} \phi \xi_{v}\right\}-\sum_{\nu=1}^{3}\left\{\left(\operatorname{Tr} \phi_{\nu} \phi\right) \eta(X)-\eta\left(\phi_{\nu} \phi X\right)\right\} \xi_{v}+h A X-A^{2} X, \tag{3.1}
\end{align*}
$$

where $h$ denotes the trace of the shape operator $A$ of $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$. From the formula $J J_{v}=J_{v} J$, $\operatorname{Tr} J J_{v}=0, v=1,2,3$ we calculate the following for any basis $\left\{e_{1}, \ldots, e_{4 m-1}, N\right\}$ of the tangent space of $G_{2}\left(\mathbb{C}^{m+2}\right)$

$$
\begin{align*}
0 & =\operatorname{Tr} J J_{v} \\
& =\sum_{k=1}^{4 m-1} g\left(J J_{v} e_{k}, e_{k}\right)+g\left(J J_{v} N, N\right) \\
& =\operatorname{Tr} \phi \phi_{v}-\eta_{v}(\xi)-g\left(J_{v} N, J N\right) \\
& =\operatorname{Tr} \phi \phi_{v}-2 \eta_{v}(\xi) \tag{3.2}
\end{align*}
$$

and

$$
\begin{align*}
\left(\phi_{v} \phi\right)^{2} X & =\phi_{\nu} \phi\left(\phi \phi_{v} X-\eta_{v}(X) \xi+\eta(X) \xi_{v}\right) \\
& =\phi_{v}\left(-\phi_{v} X+\eta\left(\phi_{v} X\right) \xi\right)+\eta(X) \phi_{v}{ }^{2} \xi \\
& =X-\eta_{v}(X) \xi_{v}+\eta\left(\phi_{v} X\right) \phi_{\nu} \xi+\eta(X)\left\{-\xi+\eta_{v}(\xi) \xi\right\} . \tag{3.3}
\end{align*}
$$

Substituting (3.2) and (3.3) into (3.1), we have

$$
\begin{align*}
S X & =(4 m+10) X-3 \eta(X) \xi-3 \sum_{v=1}^{3} \eta_{v}(X) \xi_{v}+\sum_{v=1}^{3}\left\{\eta_{\nu}(\xi) \phi_{\nu} \phi X-X-\eta\left(\phi_{v} X\right) \phi_{\nu} \xi-\eta(X) \eta_{v}(\xi) \xi_{v}\right\}+h A X-A^{2} X \\
& =(4 m+7) X-3 \eta(X) \xi-3 \sum_{v=1}^{3} \eta_{v}(X) \xi_{v}+\sum_{v=1}^{3}\left\{\eta_{v}(\xi) \phi_{\nu} \phi X-\eta\left(\phi_{\nu} X\right) \phi_{\nu} \xi-\eta(X) \eta_{v}(\xi) \xi_{v}\right\}+h A X-A^{2} X . \tag{3.4}
\end{align*}
$$

Now let us take a covariant derivative of $S \phi+\phi S=2 k \phi, k=$ const. Then it gives that

$$
\begin{equation*}
\left(\nabla_{Y} S\right) \phi X+S\left(\nabla_{Y} \phi\right) X+\left(\nabla_{Y} \phi\right) S X+\phi\left(\nabla_{Y} S\right) X=2 k\left(\nabla_{Y} \phi\right) X . \tag{3.5}
\end{equation*}
$$

Then the first term of (3.5) becomes

$$
\begin{aligned}
\left(\nabla_{Y} S\right) \phi X= & -3 g(\phi A Y, \phi X) \xi-3 \sum_{v=1}^{3}\left\{q_{v+2}(Y) \eta_{v+1}(\phi X)-q_{v+1}(Y) \eta_{v+2}(\phi X)+g\left(\phi_{v} A Y, \phi X\right)\right\} \xi_{v} \\
& -3 \sum_{v=1}^{3} \eta_{v}(\phi X)\left\{q_{v+2}(Y) \xi_{v+1}-q_{v+1}(Y) \xi_{v+2}+\phi_{v} A \phi X\right\} \\
& +\sum_{v=1}^{3}\left[Y\left(\eta_{v}(\xi)\right) \phi_{v} \phi^{2} X+\eta_{v}(\xi)\left\{-q_{v+1}(Y) \phi_{v+2} \phi^{2} X\right.\right. \\
& \left.+q_{v+2}(Y) \phi_{v+1} \phi^{2} X+\eta_{v}\left(\phi^{2} X\right) A Y-g\left(A Y, \phi^{2} X\right) \xi_{v}\right\} \\
& -\eta_{v}(\xi) g(A Y, \phi X) \phi_{v} \xi-g\left(\phi A Y, \phi_{v} \phi X\right) \phi_{v} \xi \\
& +\left\{q_{v+1}(Y) \eta\left(\phi_{v+2} \phi X\right)-q_{v+2}(Y) \eta\left(\phi_{v+1} \phi X\right)-\eta_{v}(\phi X) \eta(A Y)+\eta\left(\xi_{v}\right) g(A Y, \phi X)\right\} \phi_{v} \xi \\
& -\eta\left(\phi_{v} \phi X\right)\left\{q_{v+2}(Y) \phi_{v+1} \xi-q_{v+1}(Y) \phi_{v+2} \xi+\phi_{v} \phi A Y-\eta(A Y) \xi_{v}+\eta\left(\xi_{v}\right) A Y\right\} \\
& \left.-g(\phi A Y, \phi X) \eta_{v}(\xi) \xi_{v}\right]+(Y h) A \phi X+h\left(\nabla_{Y} A\right) \phi X-\left(\nabla_{Y} A^{2}\right) \phi X .
\end{aligned}
$$

The second term of (3.5) becomes

$$
\begin{aligned}
S\left(\nabla_{Y} \phi\right) X= & \eta(X)\left[(4 m+7) A Y-3 \eta(A Y) \xi-3 \sum_{v=1}^{3} \eta_{v}(A Y) \xi_{v}+\sum_{v=1}^{3}\left\{\eta_{v}(\xi) \phi_{v} \phi A Y-\eta\left(\phi_{v} A Y\right) \phi_{v} \xi-\eta(A Y) \eta_{v}(\xi) \xi_{v}\right\}\right. \\
& \left.+h A^{2} Y-A^{3} Y\right]-g(A Y, X)\left[(4 m+7) \xi-3 \xi-4 \sum_{v=1}^{3} \eta_{v}(\xi) \xi_{v}+h A \xi-A^{2} \xi\right] .
\end{aligned}
$$

The third term of (3.5) gives
$\left(\nabla_{Y} \phi\right) S X=\eta(S X) A Y-g(A Y, S X) \xi$,
and the fourth term of (3.5) is given by

$$
\begin{aligned}
\phi\left(\nabla_{Y} S\right) X= & -3 \eta(X) \phi^{2} A Y-3 \sum_{v=1}^{3}\left\{q_{v+2}(Y) \eta_{v+1}(X)-q_{v+1}(Y) \eta_{v+2}(X)+g\left(\phi_{v} A Y, \phi X\right)\right\} \phi \xi_{v} \\
& -3 \sum_{v=1}^{3} \eta_{v}(X)\left\{q_{v+2}(Y) \phi \xi_{v+1}-q_{v+1}(Y) \phi \xi_{v+2}+\phi \phi_{v} A Y\right\} \\
& +\sum_{v=1}^{3}\left[Y\left(\eta_{v}(\xi)\right) \phi \phi_{v} \phi X+\eta_{v}(\xi)\left\{-q_{v+1}(Y) \phi \phi_{v+2} \phi X\right.\right. \\
& \left.+q_{v+2}(Y) \phi \phi_{v+1} \phi X+\eta_{v}(\phi X) \phi A Y-g(A Y, \phi X) \phi \xi_{v}\right\} \\
& +\eta_{v}(\xi)\left\{\eta(X) \phi \phi_{v} A Y-g(A Y, X) \phi \phi_{\nu} \xi\right\}-g\left(\phi A Y, \phi_{v} X\right) \phi \phi_{v} \xi \\
& +\left\{q_{v+1}(Y) \eta\left(\phi_{v+2} X\right)-q_{v+2}(Y) \eta\left(\phi_{v+1} X\right)-\eta_{v}(X) \eta(A Y)+\eta\left(\xi_{v}\right) g(A Y, X)\right\} \phi \phi_{v} \xi \\
& -\eta\left(\phi_{v} X\right)\left\{q_{v+2}(Y) \phi \phi_{v+1} \xi-q_{v+1}(Y) \phi \phi_{v+2} \xi+\phi \phi_{v} \phi A Y-\eta(A Y) \phi \xi_{v}+\eta\left(\xi_{v}\right) \phi A Y\right\} \\
& \left.-g(\phi A Y, X) \eta_{v}(\xi) \phi \xi_{v}-\eta(X) Y\left(\eta_{v}(\xi)\right) \phi \xi_{v}-\eta(X) \eta_{v}(\xi) \phi \nabla_{Y} \xi_{v}\right] \\
& +(Y h) \phi A X+h \phi\left(\nabla_{Y} A\right) X-\phi\left(\nabla_{Y} A^{2}\right) X .
\end{aligned}
$$

Putting $X=\xi$ into (3.5) and using the structure vector $\xi$ is principal, that is, $A \xi=\alpha \xi$, then we have

$$
\begin{aligned}
& S\left(\nabla_{Y} \phi\right) \xi+\left(\nabla_{Y} \phi\right) S \xi+\phi\left(\nabla_{Y} S\right) \xi=\left[(4 m+7) A Y-3 \eta(A Y) \xi-3 \sum_{\nu=1}^{3} \eta_{\nu}(A Y) \xi_{v}\right. \\
& +\sum_{\nu=1}^{3}\left\{\eta_{\nu}(\xi) \phi_{\nu} \phi A Y-\eta\left(\phi_{\nu} \phi A Y\right) \phi_{\nu} \xi-\alpha \eta(Y) \eta_{\nu}(\xi) \xi_{v}\right\} \\
& \left.+h A^{2} Y-A^{3} Y\right]-\alpha \eta(Y)\left[4(m+1) \xi-4 \sum_{v=1}^{3} \eta_{v}(\xi) \xi_{v}+\left(\alpha h-\alpha^{2}\right) \xi\right] \\
& +\left[\left\{4(m+1)+h \alpha-\alpha^{2}\right\}-4 \sum_{\nu=1}^{3} \eta_{v}(\xi)^{2}\right] A Y-3 \eta(X) \phi^{2} A Y \\
& -\left\{\left\{4(m+1) \alpha+h \alpha^{2}-\alpha^{3}\right\} \eta(Y)-4 \sum_{\nu=1}^{3} \eta_{\nu}(\xi) \eta_{\nu}(A Y)\right\} \xi \\
& -3 \sum_{\nu=1}^{3}\left\{q_{v+2}(Y) \eta_{v+1}(\xi)-q_{v+1}(Y) \eta_{\nu+2}(\xi)+\eta_{\nu}(\phi A Y)\right\} \phi \xi_{v} \\
& -3 \sum_{v=1}^{3} \eta_{\nu}(\xi)\left\{q_{v+2}(Y) \phi \xi_{v+1}-q_{v+1}(Y) \phi \xi_{v+2}+\phi \phi_{v} A Y\right\} \\
& +\sum_{\nu=1}^{3}\left[\eta_{\nu}(\xi)\left\{\phi \phi_{\nu} A Y-\alpha \eta(Y) \phi^{2} \xi_{v}\right\}-g\left(\phi A Y, \phi \xi_{v}\right) \phi^{2} \xi_{v}\right. \\
& \left.-Y\left(\eta_{v}(\xi)\right) \phi \xi_{v}-\eta_{v}(\xi) \phi \nabla_{Y} \xi_{v}\right]+h \phi\left(\nabla_{Y} A\right) \xi-\phi\left(\nabla_{Y} A^{2}\right) \xi .
\end{aligned}
$$

From this, putting $Y=\xi$ into the above formula, we have the following

$$
0=\sum_{v=1}^{3}\left\{q_{v+2}(\xi) \eta_{v+1}(\xi)-q_{v+1}(\xi) \eta_{v+2}(\xi)\right\} \phi \xi_{v}+\sum_{v=1}^{3} \eta_{v}(\xi)\left\{q_{v+2}(\xi) \phi \xi_{v+1}-q_{v+1}(\xi) \phi \xi_{v+2}+\alpha \phi^{2} \xi_{v}\right\}
$$

Now in order to show that $\xi$ belongs to either the distribution $\mathfrak{D}$ or to the distribution $\mathfrak{D}^{\perp}$, let us assume that $\xi=X_{1}+X_{2}$ for some $X_{1} \in \mathfrak{D}$ and $X_{2} \in \mathfrak{D}^{\perp}$. Then it follows that

$$
\begin{align*}
0= & \sum_{\nu=1}^{3}\left\{q_{v+2}(\xi) \eta_{v+1}(\xi)-q_{v+1}(\xi) \eta_{v+2}(\xi)\right\}\left(\phi_{v} X_{1}+\phi_{\nu} X_{2}\right) \\
& +\sum_{\nu=1}^{3} \eta_{v}(\xi)\left\{q_{v+2}(\xi)\left(\phi_{v+1} X_{1}+\phi_{v+1} X_{2}\right)-q_{v+1}(\xi)\left(\phi_{v+2} X_{1}+\phi_{v+2} X_{2}\right)-\alpha \xi_{v}+\alpha \eta\left(\xi_{v}\right)\left(X_{1}+X_{2}\right)\right\} \tag{3.6}
\end{align*}
$$

Then by comparing $\mathfrak{D}$ and $\mathfrak{D}^{\perp}$ component of (3.6), we have respectively

$$
\begin{align*}
0= & \sum_{\nu=1}^{3}\left\{q_{v+2}(\xi) \eta_{v+1}(\xi)-q_{v+1}(\xi) \eta_{v+2}(\xi)\right\} \phi_{v} X_{1}+\alpha \sum_{v=1}^{3} \eta_{v}(\xi)^{2} X_{1} \\
& +\sum_{v=1}^{3} \eta_{\nu}(\xi)\left\{q_{v+2}(\xi) \phi_{v+1} X_{1}-q_{v+1}(\xi) \phi_{v+2} X_{1}\right\}  \tag{3.7}\\
0= & \sum_{v=1}^{3}\left\{q_{v+2}(\xi) \eta_{v+1}(\xi)-q_{v+1}(\xi) \eta_{v+2}(\xi)\right\} \phi_{v} X_{2} \\
& +\sum_{v=1}^{3} \eta_{v}(\xi)\left\{q_{v+2}(\xi) \phi_{v+1} X_{2}-q_{v+1}(\xi) \phi_{v+2} X_{2}-\alpha \xi_{v}+\alpha \eta\left(\xi_{v}\right) X_{2}\right\} \tag{3.8}
\end{align*}
$$

Taking an inner product (3.7) with $X_{1}$, we have

$$
\begin{equation*}
\alpha \sum_{\nu=1}^{3} \eta_{\nu}(\xi)^{2}=0 \tag{3.9}
\end{equation*}
$$

Then $\alpha=0$ or $\eta_{\nu}(\xi)=0$ for $v=1,2,3$. So for a non-vanishing geodesic Reeb flow we have $\eta_{v}(\xi)=0, v=1$, 2, 3. This means that $\xi \in \mathfrak{D}$, which makes a contradiction for our assumption $\xi=X_{1}+X_{2}$. Including this one, we are able to assert the following.

Lemma 3.1. Let $M$ be a Hopf hypersurface in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with pseudo anti-commuting Ricci tensor. Then the Reeb vector $\xi$ belongs to either the distribution $\mathfrak{D}$ or the distribution $\mathfrak{D}^{\perp}$.

Proof. When the geodesic Reeb flow is non-vanishing, that is $\alpha \neq 0$, (3.9) gives $\xi \in \mathfrak{D}$. When the geodesic Reeb flow is vanishing, we differentiate $A \xi=0$. Then by Berndt and Suh [13] we know that

$$
\sum_{\nu=1}^{3} \eta_{\nu}(\xi) \eta_{\nu}(\phi Y)=0
$$

From this, by replacing $Y$ by $\phi Y$, it follows that

$$
\sum_{\nu=1}^{3} \eta_{v}^{2}(\xi) \eta(Y)=0
$$

So if there are some $Y \in \mathfrak{D}$ such that $\eta(Y) \neq 0$, then $\eta_{v}(\xi)=0$ for $v=1,2,3$. This means that $\xi \in \mathfrak{D}$. If $\eta(Y)=0$ for any $Y \in \mathfrak{D}$, then we know $\xi \in \mathfrak{D}^{\perp}$.

## 4. Real hypersurfaces with geodesic Reeb flow satisfying $\boldsymbol{\xi} \in \mathfrak{D}$

Let us consider a Hopf hypersurface $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with pseudo-commuting Ricci tensor, that is, $S \phi+\phi S=2 k \phi, k=$ const. Then in this section, by Lemma 3.1, we consider pseudo-commuting hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with $\xi \in \mathfrak{D}$. Then by a theorem due to Lee and Suh [19], $M$ is locally congruent to a tube of radius $r$ over a totally real and totally geodesic $\mathbb{Q} P^{m}$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$.

Concerned with such kind of tube we are able to recall a proposition given by Berndt and Suh [11] as follows:
Proposition A. Let $M$ be a connected real hypersurface of $G_{2}\left(\mathbb{C}^{m+2}\right)$. Suppose that $A \mathfrak{D} \subset \mathfrak{D}, A \xi=\alpha \xi$, and $\xi$ is tangent to $\mathfrak{D}$. Then the quaternionic dimension $m$ of $G_{2}\left(\mathbb{C}^{m+2}\right)$ is even, say $m=2 n$, and $M$ has five distinct constant principal curvatures

$$
\alpha=-2 \tan (2 r), \quad \beta=2 \cot (2 r), \quad \gamma=0, \quad \lambda=\cot (r), \quad \mu=-\tan (r)
$$

with some $r \in(0, \pi / 4)$. The corresponding multiplicities are

$$
m(\alpha)=1, \quad m(\beta)=3=m(\gamma), \quad m(\lambda)=4 n-4=m(\mu)
$$

and the corresponding eigenspaces are

$$
T_{\alpha}=\mathbb{R} \xi, \quad T_{\beta}=\mathfrak{J} J \xi, \quad T_{\gamma}=\mathfrak{J} \xi, T_{\lambda}, T_{\mu}
$$

where

$$
T_{\lambda} \oplus T_{\mu}=(\mathbb{H} \mathbb{C} \xi)^{\perp}, \quad \mathfrak{J} T_{\lambda}=T_{\lambda}, \quad \mathfrak{J} T_{\mu}=T_{\mu}, \quad J T_{\lambda}=T_{\mu}
$$

Now it remains only to check whether the Ricci tensor for real hypersurfaces of type (B) in Theorem A is pseudo anticommuting or not. In order to do this, first let us calculate the following

$$
S X=(4 m+7) X-3 \eta(X) \xi-3 \sum_{\nu=1}^{3} \eta_{\nu}(X) \xi_{v}+\sum_{\nu=1}^{3}\left\{\eta_{v}(\xi) \phi_{\nu} \phi X-\eta\left(\phi_{\nu} X\right) \phi_{\nu} \xi-\eta(X) \eta_{\nu}(\xi) \xi_{v}\right\}+h A X-A^{2} X
$$

From this, by using the formula in Section 2, we have

$$
\begin{equation*}
S \phi X=(4 m+7) \phi X-3 \sum_{\nu=1}^{3} \eta_{v}(\phi X) \xi_{v}-\sum_{\nu=1}^{3}\left\{\eta_{v}(\xi) \phi_{\nu} X-\eta_{v}(X) \phi_{\nu} \xi\right\}+h A X-A^{2} X \tag{4.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\phi S X=(4 m+7) \phi X-3 \sum_{\nu=1}^{3} \eta_{\nu}(X) \phi \xi_{v}-\sum_{\nu=1}^{3}\left\{\eta_{v}(\xi) \phi_{\nu} X-\eta\left(\phi_{\nu} X\right) \xi_{v}\right\}+h \phi A X-\phi A^{2} X \tag{4.2}
\end{equation*}
$$

Then $S \phi+\phi S=2 k \phi$ becomes

$$
\begin{align*}
2 k \phi X= & 2(4 m+7) \phi X-2 \sum_{v=1}^{3} \eta_{v}(\phi X) \xi_{v}-2 \sum_{v=1}^{3} \eta_{v}(X) \phi \xi_{v} \\
& -2 \sum_{v=1}^{3}\left\{\eta_{v}(\xi) \phi_{v} X+h(A \phi+\phi A) X-\left(A^{2} \phi+\phi A^{2}\right) X\right\} \tag{4.3}
\end{align*}
$$

Now by proposition A let us check the formula (4.3) as follows:
Case I. $X=\xi \in \mathfrak{D}$

$$
0=-2 \sum_{\nu=1}^{3} \eta_{\nu}(\xi) \phi \xi_{v}-2 \sum_{\nu=1}^{3} \eta_{\nu}(\xi) \phi_{\nu} \xi=-4 \sum_{\nu=1}^{3} \eta_{\nu}(\xi) \phi \xi_{v}
$$

The right side also vanishes. So we have this case.
Case II. $X=\xi_{1} \in \mathfrak{D}^{\perp}$
Proposition A gives $A \phi \xi_{1}=0$. Then it satisfies

$$
\begin{aligned}
2 k \phi \xi_{1} & =2(4 m+7) \phi \xi_{1}-2\left\{\eta_{2}\left(\phi \xi_{1}\right) \xi_{2}+\eta_{3}\left(\phi \xi_{1}\right) \xi_{3}\right\}-2 \phi \xi_{1}+h \phi A \xi_{1}-\phi A^{2} \xi_{1} \\
& =\left\{2(4 m+7)-2+\beta h-\beta^{2}\right\} \phi \xi_{1}
\end{aligned}
$$

for $2 k=2(4 m+7)-2+\beta h-\beta^{2}$. This also holds for $\xi_{2}$ and $\xi_{3}$.
Case III. $X=\phi \xi_{1} \in T_{\gamma}, \gamma=0$.
Then $A \phi \xi_{1}=0$ implies that (4.3) holds

$$
\begin{aligned}
-2 k \xi_{1} & =2(4 m+7)\left(-\xi_{1}+\xi\right)+2 \xi_{1}+h A \phi^{2} \xi_{1}-A^{2} \phi^{2} \xi_{1} \\
& =\left\{-2(4 m+7)+2-\beta h+\beta^{2}\right\} \xi_{1}
\end{aligned}
$$

for $2 k=2(4 m+7)-2+\beta h-\beta^{2}$. This also holds for $\phi \xi_{2}$ and $\phi \xi_{3}$.
Case IV. $X \in T_{\lambda}, \lambda=\cot r$.
Then $A X=\lambda X, A \phi X=\mu \phi X, A^{2} \phi X=\mu \phi X$ and $\phi A^{2} X=\lambda^{2} \phi X$. Using these formulas, we have

$$
\begin{aligned}
2 k \phi X & =2(4 m+7) \phi X+h(A \phi+\phi A) X-\left(A^{2} \phi+\phi A^{2}\right) X \\
& =\left\{2(4 m+7)+h \beta-\left(\beta^{2}+2\right)\right\} \phi X .
\end{aligned}
$$

This case also becomes $2 k=2(4 m+7)-2+\beta h-\beta^{2}$.
Case V. $X \in T_{\mu}, \mu=-\tan r$.
Then $A X=\mu X, A \phi X=\lambda \phi X$ and $A^{2} \phi X=\lambda^{2} \phi X$ give for (4.3) as follows:

$$
\begin{aligned}
2 k \phi X & =2(4 m+7) \phi X+h(A \phi+\phi A) X-\left(A^{2} \phi+\phi A^{2}\right) X \\
& =\left\{2(4 m+7)+h(\mu+\lambda)-\left(\mu^{2}+\lambda 2\right)\right\} \phi X .
\end{aligned}
$$

This case also becomes $2 k=2(4 m+7)-2+\beta h-\beta^{2}$.
So summing up all cases mentioned above, real hypersurfaces of type (B) satisfy pseudo anti-commuting condition $S \phi+\phi S=2 k \phi$ for $2 k=2(4 m+7)-2+\beta h-\beta^{2}$, where $\beta=2 \cot 2 r$ and $h=\operatorname{Tr} A$ denotes the mean curvature of type (B).

## 5. Pseudo anti-commuting real hypersurfaces with $\xi \in \mathfrak{D}^{\perp}$

Now let us consider a Hopf hypersurface $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with pseudo anti-commuting Ricci tensor and $\xi \in \mathfrak{D}^{\perp}$. Now differentiating $S \phi+\phi S=2 k \phi$ gives

$$
\left(\nabla_{Y} S\right) \phi X+S\left(\nabla_{Y} \phi\right) X+\left(\nabla_{Y} \phi\right) S X+\phi\left(\nabla_{Y} S\right) X=2 k\left(\nabla_{Y} \phi\right) X .
$$

In this section by Lemma 3.1 we only discuss the geodesic Reeb flow $\xi$ belongs to the distribution $\mathfrak{D}^{\perp}$. Since we have assumed that $\xi \in \mathfrak{D}^{\perp}=\operatorname{Span}\left\{\xi_{1}, \xi_{2}, \xi_{3}\right\}$, there exists an Hermitian structure $J_{1} \in \mathfrak{J}$ such that $J N=J_{1} N$, that is, $\xi=\xi_{1}$. Then it follows that

$$
\begin{equation*}
\phi \xi_{2}=\phi_{2} \xi=\phi_{2} \xi_{1}=-\xi_{3}, \quad \phi \xi_{3}=\phi_{3} \xi_{1}=-\xi_{2} \tag{5.1}
\end{equation*}
$$

From this, together with the expression of (3.4) and $\xi \in \mathfrak{D}^{\perp}$, we have

$$
\begin{align*}
(4 m & +1) g(A X, Y) \xi-3\left[\left\{q_{3}(Y) \eta_{3}(X)+q_{2}(Y) \eta_{2}(X)\right\} \xi_{1}-q_{1}(Y) \eta_{2}(X) \xi_{2}-q_{1}(Y) \eta_{3}(X) \xi_{3}\right] \\
& +2 \eta(X) \eta_{2}(A Y) \xi_{2}+2 \eta(X) \eta_{3}(A Y) \xi_{3}+\sum_{v=1}^{3} \eta_{v}(X) \phi_{\nu} \phi A Y \\
& +(Y h) A \phi X+h\left(\nabla_{Y} A\right) \phi X-\left(\nabla_{Y} A^{2}\right) \phi X+\eta(X)\left\{h A^{2} Y-A^{3} Y\right\} \\
& -\left\{g(A Y, S X)+\eta_{3}(X) \eta_{3}(A Y)+\eta_{2}(X) \eta_{2}(A Y)\right\} \xi+4\left[g\left(\phi_{2} A Y, X\right) \xi_{3}-g\left(\phi_{3} A Y, X\right) \xi_{2}\right] \\
& -3 \sum_{\nu=1}^{3} \eta_{v}(X) \phi \phi_{v} A Y+4 \sum_{\nu=1}^{3} g\left(\phi A Y, \phi_{v} X\right) \xi_{v}+\eta_{3}(X) \phi_{2} A Y-\eta_{2}(X) \phi_{3} A Y \\
& +(Y h) \phi A X+h \phi\left(\nabla_{Y} A\right) X-\phi\left(\nabla_{Y} A^{2}\right) X \\
= & 2 k\{\eta(Y) A X-g(A Y, X) \xi\} . \tag{5.2}
\end{align*}
$$

Now putting $X=\xi$ in (5.2), we have

$$
\begin{aligned}
& (4 m+1) g(A \xi, Y) \xi+2 \eta_{2}(A Y) \xi_{2}+2 \eta_{3}(A Y) \xi_{3}+\phi_{1} \phi A Y+h A^{2} Y-A^{3} Y \\
& \quad-g(A Y, S \xi) \xi+4\left\{g\left(\phi_{2} A Y, \xi\right) \xi_{3}-g\left(\phi_{3} A Y, \xi\right) \xi_{2}\right\}-3 \phi \phi_{1} A Y+4 g\left(\phi A Y, \phi_{2} \xi\right) \xi_{2}+4 g\left(\phi A Y, \phi_{3} \xi\right) \xi_{3} \\
& \quad+h \phi\left(\nabla_{Y} A\right) \xi-\phi\left(\nabla_{Y} A^{2}\right) \xi=0 .
\end{aligned}
$$

From this, if we use the following formulas

$$
\begin{aligned}
S \xi & =4(m+1) \xi-4 \sum_{v=1}^{3} \eta_{v}(\xi) \xi_{v}+h A \xi-A^{2} \xi \\
& =\left(4 m+h \alpha-\alpha^{2}\right) \xi
\end{aligned}
$$

and

$$
g(A Y, S \xi)=\alpha\left(4 m+h \alpha-\alpha^{2}\right) \eta(Y)
$$

then it follows that

$$
\begin{equation*}
\phi_{1} \phi A Y+h A^{2} Y-A^{3} Y=-10 \eta_{2}(A Y) \xi_{2}-10 \eta_{3}(A Y) \xi_{3}+h \alpha A Y-\alpha^{2} A Y+h \phi A \phi A Y-\phi A^{2} \phi A Y+3 \phi \phi_{1} A Y \tag{5.3}
\end{equation*}
$$

On the other hand, by the equation of Codazzi in [11] (see p. 6), we have

$$
\begin{align*}
A \phi A Y & =\phi Y+\sum_{v=1}^{3}\left\{\eta_{v}(Y) \phi \xi_{v}+\eta_{v}(\phi Y) \xi_{v}+\eta_{v}(\xi) \phi_{v} Y-2 \eta(Y) \eta_{v}(\xi) \phi \xi_{v}-2 \eta_{v}(\xi) \eta_{v}(\phi Y) \xi\right\}+\alpha(A \phi+\phi A) Y \\
& =\phi Y+\phi_{1} Y+\eta_{2}(Y) \phi \xi_{2}+\eta_{3}(Y) \phi \xi_{3}+\eta_{2}(\phi Y) \xi_{2}+\eta_{3}(\phi Y) \xi_{3}+\alpha(A \phi+\phi A) Y \tag{5.4}
\end{align*}
$$

So for any $Y \in \mathfrak{D}$ (5.4) gives that $A \phi A Y=\phi Y+\phi_{1} Y+\alpha(A \phi+\phi A) Y$. This implies

$$
\phi A^{2} \phi A Y=\phi A \phi Y+\phi A \phi_{1} Y+\alpha \phi A(A \phi+\phi A) Y
$$

From this, together with (5.3), it follows that

$$
\begin{align*}
\phi_{1} \phi A Y+h A^{2} Y-A^{3} Y= & -10 \eta_{2}(A Y) \xi_{2}-10 \eta_{3}(A Y) \xi_{3}+\alpha h A Y-\alpha^{2} A Y+\alpha h \phi(A \phi+\phi A) Y \\
& +h\left(-Y+\phi \phi_{1} Y\right)-\phi A \phi Y-\phi A \phi_{1} Y-\alpha \phi A(A \phi+\phi A) Y+3 \phi \phi_{1} A Y \tag{5.5}
\end{align*}
$$

On the other hand, we calculate the following

$$
\begin{aligned}
& S \phi Y=(4 m+7) \phi Y-3 \eta_{2}(\phi Y) \xi_{2}-3 \eta_{3}(\phi Y) \xi_{3}+\phi_{1} \phi^{2} Y-\eta\left(\phi_{2} \phi Y\right) \phi_{2} \xi-\eta\left(\phi_{3} \phi Y\right) \phi_{3} \xi+h A \phi Y-A^{2} \phi Y, \\
& \phi S Y=(4 m+7) \phi Y-3 \sum_{v=1}^{3} \eta_{\nu}(Y) \phi \xi_{v}+\phi \phi_{1} \phi Y-\eta\left(\phi_{2} Y\right) \phi_{2} \xi-\eta\left(\phi_{3} Y\right) \phi_{3} \xi+h \phi A Y-\phi A^{2} Y
\end{aligned}
$$

So for any $Y \in \mathfrak{D}$ the condition $S \phi+\phi S=2 k \phi$ implies that

$$
2(4 m+7) \phi Y-\phi_{1} Y+h A \phi Y-A^{2} \phi Y+\phi \phi_{1} \phi Y+h \phi A Y-\phi A^{2} Y=2 k \phi Y .
$$

Then by replacing $Y$ by $\phi Y$ for $Y \in \mathfrak{D}$ we have

$$
\begin{equation*}
A^{3} Y-h A^{2} Y-\{2(4 m+7)-2 k\} A Y=A \phi_{1} \phi Y+A \phi \phi_{1} Y-h A \phi A \phi Y+A \phi A^{2} \phi Y \tag{5.6}
\end{equation*}
$$

Now by using (5.4) for $Y \in \mathfrak{D}$, the terms in the right side becomes respectively

$$
A \phi A \phi Y=-Y+\phi_{1} \phi Y+\alpha(A \phi+\phi A) \phi Y
$$

and

$$
A \phi A^{2} \phi Y=\phi A \phi Y+\phi_{1} A \phi Y+\eta_{2}(A \phi Y) \phi \xi_{2}+\eta_{3}(A \phi Y) \phi \xi_{3}+\eta_{2}(\phi A \phi Y) \xi_{2}+\eta_{3}(\phi A \phi Y) \xi_{3}+\alpha(A \phi+\phi A) \phi Y
$$

From these, together with (5.5) and (5.6), we have

$$
\begin{aligned}
& \phi_{1} \phi A Y-2\{4 m+7-k\} A Y-A \phi_{1} \phi Y-A \phi \phi_{1} Y+h A \phi A \phi Y-A \phi A^{2} \phi Y \\
& =-10 \eta_{2}(A Y) \xi_{2}-10 \eta_{3}(A Y) \xi_{3}+\alpha h A Y-\alpha^{2} A Y+\alpha h \phi(A \phi+\phi A) Y \\
& \quad+h\left(-Y+\phi \phi_{1} Y\right)-\phi A \phi Y-\phi A \phi_{1} Y-\alpha \phi A(A \phi+\phi A) Y+3 \phi \phi_{1} A Y .
\end{aligned}
$$

Substituting the above formulas into this, we have

$$
\begin{aligned}
& \phi_{1} \phi A Y-\{2(4 m+7-k)-\alpha(\alpha-h)\} A Y-A \phi_{1} \phi Y-A \phi \phi_{1} Y \\
& \quad+h\left\{-Y+\phi_{1} \phi Y+\alpha(A \phi+\phi A) \phi Y\right\}-\phi A \phi Y-\phi_{1} A \phi Y-\alpha(A \phi+\phi A) A \phi Y \\
& \quad-\eta_{2}(A \phi Y) \phi \xi_{2}-\eta_{3}(A \phi Y) \phi \xi_{3}-\eta_{2}(\phi A \phi Y) \xi_{2}-\eta_{3}(\phi A \phi Y) \xi_{3} \\
& = \\
& \quad-10 \eta_{2}(A Y) \xi_{2}-10 \eta_{3}(A Y) \xi_{3}+\alpha h \phi(A \phi+\phi A) Y+h\left(-Y+\phi \phi_{1} Y\right) \\
& \quad-\phi A \phi Y-\phi A \phi_{1} Y-\alpha \phi A(A \phi+\phi A) Y+3 \phi \phi_{1} A Y .
\end{aligned}
$$

From this, if we use the following formulas obtained from (5.4)

$$
\alpha A \phi A \phi Y=-\alpha Y+\alpha \phi_{1} \phi Y+\alpha^{2}(A \phi+\phi A) \phi Y
$$

and

$$
\alpha \phi A \phi A Y=-\alpha Y+\alpha \phi \phi_{1} Y+\alpha^{2} \phi(A \phi+\phi A) Y
$$

then it follows that

$$
\begin{aligned}
& \phi_{1} \phi A Y-\{2(4 m+7-k)-\alpha(\alpha-h)\} A Y-A \phi_{1} \phi Y-A \phi \phi_{1} Y-\phi_{1} A \phi Y+\alpha Y-\alpha \phi_{1} \phi Y-\alpha^{2}(A \phi+\phi A) \phi Y \\
& \quad-\eta_{2}(A \phi Y) \phi \xi_{2}-\eta_{3}(A \phi Y) \phi \xi_{3}-\eta_{2}(\phi A \phi Y) \xi_{2}-\eta_{3}(\phi A \phi Y) \xi_{3} \\
& =-10 \eta_{2}(A Y) \xi_{2}-10 \eta_{3}(A Y) \xi_{3}-\phi A \phi_{1} Y+\alpha Y-\alpha \phi \phi_{1} Y-\alpha^{2} \phi(A \phi+\phi A) Y+3 \phi \phi_{1} A Y
\end{aligned}
$$

From this, let us take an inner product with $\xi_{2}$, then for any $Y \in \mathfrak{D}$ we have

$$
\begin{align*}
- & 2 \eta_{2}(A Y)-2 g\left(A \phi_{1} \phi Y, \xi_{2}\right)+\eta_{3}(A \phi Y)+\eta_{3}\left(A \phi_{1} Y\right) \\
& -\{2(4 m+7-k)-\alpha(\alpha-h)\} \eta_{2}(A Y)-\eta_{3}(A \phi Y)-\eta_{2}(\phi A \phi Y) \\
= & -10 \eta_{2}(A Y) \tag{5.7}
\end{align*}
$$

Then in this section we know that the distribution $\mathfrak{D}$ can be decomposed into two distributions $\mathfrak{D}_{1}$ and $\mathfrak{D}_{2}$ defined in such a way that

$$
\mathfrak{D}_{1}=\left\{Y \in \mathfrak{D} \mid \phi Y=\phi_{1} Y\right\}
$$

and

$$
\mathfrak{D}_{2}=\left\{Y \in \mathfrak{D} \mid \phi Y=-\phi_{1} Y\right\}
$$

So first let us consider the distribution $\mathfrak{D}_{1}$.

Then by a direct calculation in (5.7) for any $Y \in \mathfrak{D}_{1}$, we have

$$
\begin{equation*}
\{2(4 m+2-k)-\alpha(\alpha-h)\} \eta_{2}(A \phi Y)=0 \tag{5.8}
\end{equation*}
$$

Now let use the similar method as in taking $\xi_{2}$ in above formula. So if we take an inner product $\xi_{3}$ to the above formula, then it follows that

$$
\begin{align*}
- & 2 \eta_{3}(A Y)-2 g\left(A \phi_{1} \phi Y, \xi_{3}\right)-\eta_{2}(A \phi Y)-\eta_{2}\left(A \phi_{1} Y\right) \\
& -\{2(4 m+7-k)-\alpha(\alpha-h)\} \eta_{3}(A Y)+\eta_{2}(A \phi Y)-\eta_{3}(\phi A \phi Y) \\
= & -10 \eta_{3}(A Y) \tag{5.9}
\end{align*}
$$

Then by a straightforward calculation in (5.9) for any $Y \in \mathfrak{D}_{1}$, we have

$$
\begin{equation*}
\{2(4 m+2-k)-\alpha(\alpha-h)\} \eta_{3}(A Y)=0 . \tag{5.10}
\end{equation*}
$$

From this, we assert the following.
Lemma 5.1. Let $M$ be a Hopf pseudo anti-commuting real hypersurface in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with the Reeb vector field $\xi$ belonging to the distribution $\mathfrak{D}^{\perp}$. Then $k=4 m+2+\frac{\alpha}{2}(h-\alpha)$ or $M$ is locally congruent to a tube of radius $r$ over a totally geodesic $G_{2}\left(\mathbb{C}^{m+1}\right)$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$, where $h$ denotes the mean curvature of $M$ and $\alpha=g(A \xi, \xi)$.

Proof. Now we consider for the case $k \neq 4 m+2+\frac{\alpha}{2}(h-\alpha)$. Then (5.8) and (5.10) give $\eta_{\nu}(A Y)=0$ for any $Y \in \mathfrak{D}_{1}$. Then in order to show that $g\left(A \mathfrak{D}, \mathfrak{D}^{\perp}\right)=0$ it is sufficient to show that $\eta_{\nu}(A Y)=0$ for any $Y \in \mathfrak{D}_{2}$.

So for any $Y \in \mathfrak{D}_{2}$ (5.7) and (5.9) give the following respectively

$$
\begin{equation*}
\{6-2(4 m+7-k)+\alpha(\alpha-h)\} \eta_{2}(A Y)=2 \eta_{3}(A \phi Y) \tag{5.11}
\end{equation*}
$$

and

$$
\begin{equation*}
\{6-2(4 m+7-k)+\alpha(\alpha-h)\} \eta_{3}(A Y)=-2 \eta_{2}(A \phi Y) \tag{5.12}
\end{equation*}
$$

Now let us put $b=6-2(4 m+7-k)+\alpha(\alpha-h)$. Then we consider the following two cases.
Case I. $b \neq 0$
Then (5.11) and (5.12) give for any $Y \in \mathfrak{D}_{2}$

$$
\eta_{2}(A Y)=\frac{2}{b} \eta_{3}(A \phi Y), \quad \eta_{3}(A Y)=-\frac{2}{b} \eta_{2}(A \phi Y)
$$

Since the distribution $\mathfrak{D}_{2}$ is invariant by the structure tensor $\phi$, if we replace the vector $Y$ by $\phi Y$, it becomes

$$
\eta_{2}(A \phi Y)=-\frac{2}{b} \eta_{3}(A Y), \quad \eta_{3}(A \phi Y)=\frac{2}{b} \eta_{2}(A Y)
$$

Then it gives $\eta_{2}(A Y)=\frac{4}{b^{2}} \eta_{2}(A Y)$. This implies $\eta_{2}(A Y)=\eta_{3}(A Y)=0$ for $Y \in \mathfrak{D}_{2}$ when $b \neq 2$. When $b=2$, (5.8) and (5.10) give naturally $\eta_{2}(A Y)=0$ and $\eta_{3}(A Y)=0$ for any $Y \in \mathfrak{D}_{1}$ respectively. Moreover, from (5.11) and (5.12) it follows that

$$
\eta_{2}(A Y)=\eta_{3}(A \phi Y), \quad \eta_{3}(A Y)=-\eta_{2}(A \phi Y)
$$

for any $Y \in \mathfrak{D}_{2}$. Then by using the same method given in Suh [7, pp. 1803-1804] we can prove that $\eta_{2}(A Y)=0$ and $\eta_{3}(A Y)$ $=0$ for any $Y \in \mathfrak{D}_{2}$.
Case II. $b=0$.
(5.11) and (5.12) give $\eta_{2}(A \phi Y)=0$ and $\eta_{3}(A \phi Y)=0$ for any $Y \in \mathfrak{D}_{2}$ respectively. The invariance of the distribution $\mathfrak{D}_{2}$ under the structure tensor $\phi$ gives also $\eta_{2}(A Y)=\eta_{3}(A Y)=0$ for any $Y \in \mathfrak{D}_{2}$.

Summing up Cases I and II, we conclude that the distribution $\mathfrak{D}$ is invariant by the shape operator, that is, $g\left(A \mathfrak{D}, \mathfrak{D}^{\perp}\right)=0$. Then by Theorem A due to Berndt and Suh [11], $M$ is locally isometric to a tube of radius $r$ over the totally geodesic $G_{2}\left(\mathbb{C}^{m+1}\right)$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$. This gives our assertion.

Now we want to prove that real hypersurfaces of type (A), that is, a tube of radius $r$ over a totally geodesic $G_{2}\left(\mathbb{C}^{m+1}\right)$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$, does not admit any pseudo anti-commuting structures.

Related to this kind of hypersurfaces in Theorem A we introduce another proposition due to Berndt and Suh [11] as follows:

Proposition B. Let $M$ be a connected real hypersurface of $G_{2}\left(\mathbb{C}^{m+2}\right)$. Suppose that $A \mathfrak{D} \subset \mathfrak{D}, A \xi=\alpha \xi$, and $\xi$ is tangent to $\mathfrak{D}^{\perp}$. Let $J_{1} \in \mathfrak{J}$ be the almost Hermitian structure such that $J N=J_{1} N$. Then $M$ has three (if $r=\pi / 2$ ) or four (otherwise) distinct constant principal curvatures

$$
\alpha=\sqrt{8} \cot (\sqrt{8} r), \quad \beta=\sqrt{2} \cot (\sqrt{2} r), \quad \lambda=-\sqrt{2} \tan (\sqrt{2} r), \quad \mu=0
$$

with some $r \in(0, \pi / \sqrt{8})$. The corresponding multiplicities are

$$
m(\alpha)=1, \quad m(\beta)=2, \quad m(\lambda)=2 m-2=m(\mu)
$$

and the corresponding eigenspaces we have

$$
\begin{aligned}
& T_{\alpha}=\mathbb{R} \xi=\mathbb{R} J N \\
& T_{\beta}=\mathbb{C}^{\perp} \xi=\mathbb{C}^{\perp} N \\
& T_{\lambda}=\left\{X \mid X \perp \mathbb{H} \xi, J X=J_{1} X\right\} \\
& T_{\mu}=\left\{X \mid X \perp \mathbb{H} \xi, J X=-J_{1} X\right\}
\end{aligned}
$$

In the paper [13] due to Berndt and Suh we have given a characterization of real hypersurfaces of type $A$ in Theorem $A$ when the shape operator $A$ of $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ commutes with the structure tensor $\phi$, which is equivalent to the condition that the Reeb flow on $M$ is isometric, that is $\mathscr{L}_{\xi} g=0$, where $\mathcal{L}$ (resp. $g$ ) denotes the Lie derivative (resp. the induced Riemannian metric) of $M$ in the direction of the Reeb vector field $\xi$. Namely, Berndt and Suh [11] proved the following.

Theorem B. Let $M$ be a connected orientable real hypersurface in $G_{2}\left(\mathbb{C}^{m+2}\right), m \geq 3$. Then the Reeb flow on $M$ is isometric if and only if $M$ is an open part of a tube around some totally geodesic $G_{2}\left(\mathbb{C}^{m+1}\right)$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$.

Now let us check that real hypersurfaces of type (A) mentioned in Proposition B and Theorem B whether they satisfy pseudo anti-commuting, that is, $S \phi+\phi S=2 k \phi$. Then by Theorem B for the commuting shape operator, that is, $A \phi=\phi A$, the commuting Ricci tensor $S \phi=\phi S$ implies that $S \phi=\phi S=k \phi$, which is given by

$$
\begin{align*}
S \phi X & =(4 m+7) \phi X-3 \sum_{v=1}^{3} \eta_{\nu}(\phi X) \xi_{v}-\sum_{v=1}^{3}\left\{\eta_{v}(\xi) \phi_{v} X-\eta_{v}(X) \phi_{\nu} \xi\right\}+h A \phi X-A^{2} \phi X \\
& =k \phi X \tag{5.13}
\end{align*}
$$

Now by using Proposition B, we check case by case whether two sides in (5.13) are equal to each other as follows:
Case I. $X=\xi=\xi_{1}$
In this case it can be easily checked that two sides are equal to each other.
Case II. $X=\xi_{2}, \xi_{3}$
Then by putting $X=\xi_{2}$ in (5.13) we have

$$
\begin{aligned}
k \phi \xi_{2} & =S \phi \xi_{2}=(4 m+7) \phi \xi_{2}-3 \sum_{v=1}^{3} \eta_{\nu}\left(\phi \xi_{2}\right) \xi_{v}-\sum_{\nu=1}^{3}\left\{\eta_{v}(\xi) \phi_{\nu} \xi_{2}-\eta_{v}\left(\xi_{2}\right) \phi_{v} \xi\right\}+h A \phi \xi_{2}-A^{2} \phi \xi_{2} \\
& =-(4 m+7) \xi_{3}+3 \xi_{3}-2 \xi_{3}-h \beta \xi_{3}+\beta^{2} \xi_{3} \\
& =-\left\{(4 m+6)+h \beta-\beta^{2}\right\} \xi_{3}
\end{aligned}
$$

which gives $k=4 m+6+h \beta-\beta^{2}$.
Case III. $X \in T_{\lambda}, \lambda=-\sqrt{2} \tan (\sqrt{2} r)$.
Then $A X=\lambda X, A \phi X=\lambda \phi X$ and $A^{2} \phi X=\lambda^{2} \phi X$ gives

$$
\begin{aligned}
k \phi X & =S \phi X=(4 m+7) \phi X-\phi_{1} X+h \lambda \phi X-\lambda^{2} \phi X \\
& =\left(4 m+6+h \lambda-\lambda^{2}\right) \phi X
\end{aligned}
$$

This case becomes $k=4 m+6+h \lambda-\lambda^{2}$.
Case IV. $X \in T_{\mu}, \mu=0$.
Then $A \phi X=0$ and $A^{2} \phi X=0$ gives

$$
k \phi X=S \phi X=(4 m+7) \phi X-\phi_{1} X=(4 m+8) \phi X
$$

This means $k=4 m+8$.
By comparing Cases II and III for the constant $k$ we know $\cot ^{2}(\sqrt{2} r)=m-1$. On the other hand, from Cases III and IV we have

$$
4 m+8=4 m+6+h(-\sqrt{2} \tan \sqrt{2} r)-2 \tan ^{2} \sqrt{2} r
$$

which gives

$$
\begin{aligned}
2 & =(3 \sqrt{2} \cot \sqrt{2} r-\sqrt{2}(2 m-1) \tan \sqrt{2} r)(-\sqrt{2} \tan \sqrt{2} r)-2 \tan ^{2} \sqrt{2} r \\
& =-6+2(2 m-1) \tan ^{2} \sqrt{2} r-2 \tan ^{2} \sqrt{2} r
\end{aligned}
$$

Then it follows that $\tan ^{2} \sqrt{2} r=\frac{2}{m-1}$, which gives a contradiction. So real hypersurfaces of type $(A)$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ in Lemma 5.1 cannot be appeared. Now we prove the following.

Theorem 5.2. Let $M$ be a Hopf pseudo anti-commuting real hypersurface in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with Reeb vector field $\xi$ belonging to the distribution $\mathfrak{D}^{\perp}$. Then $k=4 m+2+\frac{\alpha}{2}(h-\alpha)$.

## 6. Ricci soliton on real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$

Let us recall that an $n$-dimensional Riemannian manifold ( $M, g$ ) is said to be Ricci soliton if there exists a smooth vector field $V \in T_{x} M, x \in M$ that satisfies

$$
\frac{1}{2}\left(\mathfrak{L}_{V} g\right)(X, Y)+\operatorname{Ric}(X, Y)=k g(X, Y), \quad X, Y \in T M
$$

where $\mathfrak{L}_{V} g$ denotes the Lie derivative of $g$ with respect to the vector field $V$ and $k$ a constant (see Chow et al. [15]). We will denote the Ricci soliton by ( $M, g, V, k$ ) and call the vector field $V$ as the potential vector field of the Ricci soliton. A Ricci soliton $(M, g, V, k)$ is said to be a stable, expanding or shrinking according to $k=0, k<0$ or $k>0$. It is known that the Ricci tensor $S$ of an Einstein hypersurface $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ is given by $S=a g$ for a constant $a$, that is, $\operatorname{Ric}(X, Y)=a g(X, Y)$ for any $X$ and $Y$ on $M$ and a Riemannian metric $g$ defined on $M$.

In this section we consider a Ricci soliton on real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with the potential Reeb vector field $\xi$. Then the Ricci soliton formula gives the following for any vector fields on $M$

$$
\begin{equation*}
\operatorname{Ric}(X, Y)+\frac{1}{2}\left(\mathfrak{L}_{\xi} g\right)(X, Y)=k g(X, Y) \tag{6.1}
\end{equation*}
$$

where $\mathfrak{L}_{\xi}$ denotes the Lie derivative along the direction of the Reeb vector field $\xi$. The formula (6.1) becomes

$$
\begin{align*}
& (4 m+7-k) X-3 \eta(X) \xi-3 \sum_{v=1}^{3} \eta_{v}(X) \xi_{v}+\sum_{v=1}^{3}\left\{\eta_{v}(\xi) \phi_{\nu} \phi X-\eta\left(\phi_{v} X\right) \phi_{\nu} \xi\right. \\
& \left.\quad-\eta(X) \eta_{v}(\xi) \xi_{v}\right\}+h A X-A^{2} X+\frac{1}{2}(\phi A-A \phi) X=0 \tag{6.2}
\end{align*}
$$

Moreover, from (6.2) it follows that

$$
\begin{aligned}
S \phi X & =k \phi X+\frac{1}{2}(A \phi-\phi A) \phi X \\
& =k \phi X-\frac{1}{2}(\phi A \phi X+A X-\alpha \eta(X) \xi)
\end{aligned}
$$

and

$$
\begin{aligned}
\phi S X & =k \phi X+\frac{1}{2}\left(\phi A \phi-\phi^{2} A\right) X \\
& =k \phi X+\frac{1}{2}(\phi A \phi X+A X-\alpha \eta(X) \xi) .
\end{aligned}
$$

Then it follows that the Ricci soliton satisfies $(S \phi+\phi S) X=2 k \phi X, k=$ const. By using Lemma 3.1, the Reeb vector $\xi$ belongs either to the distribution $\mathfrak{D}$ or the distribution $\mathfrak{D}^{\perp}$. Then we assert the following.

Lemma 6.1. Let $M$ be a Hopf Ricci soliton on real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with the potential Reeb field $\xi$. Then the soliton constant $k$ is given by

$$
\begin{aligned}
& k=4 m+h \alpha-\alpha^{2} \text { for } \xi \in \mathfrak{D}^{\perp} \\
& k=4(m+1)+h \alpha-\alpha^{2} \quad \text { for } \xi \in \mathfrak{D}
\end{aligned}
$$

Proof. The Ricci soliton constant $k$ in (6.1) becomes

$$
\begin{equation*}
k=\operatorname{Ric}(\xi, \xi)=g(S \xi, \xi)=4(m+1)-4 \sum_{v=1}^{3} \eta_{v}(\xi)^{2}+\operatorname{hg}(A \xi, \xi)-g\left(A^{2} \xi, \xi\right) \tag{6.3}
\end{equation*}
$$

because $\left(\mathfrak{L}_{\xi} g\right)(\xi, \xi)=0$. We know that the Hopf Ricci soliton satisfies the pseudo anti-commuting, so Lemma 3.1 gives that the Reeb vector field $\xi$ belongs to the distribution $\mathfrak{D}$ or $\mathfrak{D}^{\perp}$. Then putting $X=\xi$ in (6.2), we assert the results in our lemma according to the Reeb vector $\xi \in \mathfrak{D}$ or $\xi \in \mathfrak{D}^{\perp}$ as follows: For $\xi=\xi_{1} \in \mathfrak{D}^{\perp}$ in (6.3) the Ricci curvature $\operatorname{Ric}(\xi, \xi)=g(S \xi, \xi)$ becomes

$$
k=\operatorname{Ric}(\xi, \xi)=g(S \xi, \xi)=4(m+1)-4+h \alpha-\alpha^{2}
$$

so $k=4 m+h \alpha-\alpha^{2}$. For $\xi \in \mathfrak{D}$,(6.3) gives $k=4(m+1)+h \alpha-\alpha^{2}$. This gives our assertion.

From (6.2), together with (6.3), we have

$$
\begin{align*}
& \left\{4 \sum_{v=1}^{3} \eta_{v}(\xi)^{2}-\alpha(h-\alpha)+3\right\} X-3 \eta(X) \xi-3 \sum_{v=1}^{3} \eta_{\nu}(X) \xi_{v} \\
& \quad+\sum_{\nu=1}^{3}\left\{\eta_{v}(\xi) \phi_{\nu} \phi X-\eta\left(\phi_{v} X\right) \phi_{v} \xi-\eta(X) \eta_{v}(\xi) \xi_{v}\right\}+h A X-A^{2} X+\frac{1}{2}(\phi A-A \phi) X=0 . \tag{6.4}
\end{align*}
$$

Then for $\xi \in \mathfrak{D}$, (6.4) gives the following

$$
\begin{equation*}
\{3-\alpha(h-\alpha)\} X-3 \eta(X) \xi-3 \sum_{v=1}^{3} \eta_{v}(X) \xi_{v}-\sum_{v=1}^{3} \eta\left(\phi_{v} X\right) \phi_{\nu} \xi+h A X-A^{2} X+\frac{1}{2}(\phi A-A \phi) X=0 \tag{6.5}
\end{equation*}
$$

Since the Hopf Ricci soliton satisfies $S \phi+\phi S=2 k \phi$, by Theorem 1 we have two cases (i) $k=4 m+2+\frac{\alpha}{2}(h-\alpha)$ and (ii) real hypersurfaces of type (B) in Theorem A. Now first we consider the latter case (ii). Then we can use all the properties given in Proposition A in Section 4. So we can apply Proposition A to (6.5). Now, putting $X=\xi_{2}$ in (6.5), we have

$$
-\alpha(h-\alpha) \xi_{2}+\left(h \beta-\beta^{2}\right) \xi_{2}=0
$$

From this we know that $h=\alpha+\beta=\alpha+3 \beta+4(n-1)(\lambda+\mu)$. This implies $\cot r=\tan r$, which means $r=\frac{\pi}{4}$. It gives us a contradiction. So the Ricci soliton cannot be appeared in real hypersurfaces of type (B) in $G_{2}\left(\mathbb{C}^{m+2}\right)$.

Next we consider the first case (i) for $\xi \in \mathfrak{D}^{\perp}$. Since the Ricci soliton satisfies pseudo anti-commuting, we have $S \phi+\phi S=$ $2 k \phi$, so Theorem 5.2 gives $k=4 m+2+\frac{\alpha}{2}(h-\alpha)$. From this, compared with the first result $k=4 m+h \alpha-\alpha^{2}$ in Lemma 6.1 for the Hopf Ricci soliton, we know that $4=\alpha(h-\alpha)$. So the soliton constant $k$ becomes $k=4(m+1)>0$. This gives that $(M, \xi, g, 4(m+1))$ becomes a shrinking Ricci soliton. Then we give a complete proof of Theorem 2 in the introduction.

Remark 6.2. In the paper due to Pérez, Suh and Watanabe [12] we have given a classification of pseudo-Einstein real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$. But it is proper pseudo-Einstein with $c \neq 0$ so it does not satisfy the pseudo-anti commuting formula, because the quaternionic Kähler structure is included in $G_{2}\left(\mathbb{C}^{m+2}\right)$.

Remark 6.3. Related to the properties of the Ricci tensor in $G_{2}\left(\mathbb{C}^{m+2}\right)$ we have proved the non-existence of real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with parallel Ricci tensor in [17]. Motivated by such a geometric property we give a characterization of type (A) in Theorem A by the invariant Ricci tensor, that is, $\mathcal{L}_{\xi} S=0$ along the flow in the direction of the Reeb vector field $\xi$ (see [18]). Moreover, in [20] we gave a complete classification of real hypersurfaces $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$ with harmonic curvature, that is, $\delta S=0$, where $\delta$ denotes the adjoint coderivative defined on $M$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$.

Remark 6.4. When we consider a ruled real hypersurface $M_{R}=\Sigma * \times G_{2}\left(\mathbb{C}^{m+1}\right)$ in $G_{2}\left(\mathbb{C}^{m+2}\right)$, the expression of the shape operator $A \xi=\beta \xi_{2}, A \xi_{2}=\beta \xi$ and $A X=0$ for any $X$ orthogonal to $\xi=\xi_{1}$ and $\xi_{2}$ (see [21]). So the ruled real hypersurface $M_{R}$ is not Hopf. Of course, the trace of the shape operator $h$ vanishes and the principal curvature $\alpha=g(A \xi, \xi)$ also vanishes. From such a view point, by Theorem 2, there do not exist any Ricci soliton on ruled real hypersurfaces in $G_{2}\left(\mathbb{C}^{m+2}\right)$.

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[^0]:    * Corresponding author. Fax: +82 539506306.

    E-mail addresses: imsoon.jeong@gmail.com (I. Jeong), yjsuh@knu.ac.kr (Y.J. Suh).

